

IN THE SPECIFICATION:

The specification as amended below with a replacement paragraphs shows added text with underlining and deleted text with ~~strikethrough~~.

Please REPLACE the paragraph beginning at page 15, line 10, with the following paragraph:

According to the present invention, as described above, the workpiece gripped state established by the hand can be observed without stopping the robot. This prevents the tact time from being affected. Furthermore, a flexible and inexpensive system can be constructed which need not use any exclusive conveyors even for large-sized workpieces.